

R3G400-AY87-01

EC centrifugal fan - RadiPac

backward-curved



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Nominal data

Type	R3G400-AY87-01	
Motor	M3G112-IA	

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60

Method of obtaining data		ml
Speed (rpm)	min ⁻¹	2180
Power consumption	W	1850
Current draw	A	2.9
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	65.3	54.1	09 Power consumption P_{ed}	kW	1.78
02 Measurement category		A		09 Air flow q_v	m ³ /h	5490
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	712
04 Efficiency grade N		73.2	62	10 Speed (rpm) n	min ⁻¹	2160
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-122009

The efficiency values displayed for achieving conformity with the Ecodesign Regulation EU 327/2011 has been reached with defined air duct components (e.g. inlet rings).
The dimensions must be requested from ebm-papst. If other air conduction geometries are used on the installation side, the ebm-papst evaluation loses its validity/the conformity must be confirmed again.
The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2 (2a) (motors completely integrated into a product).

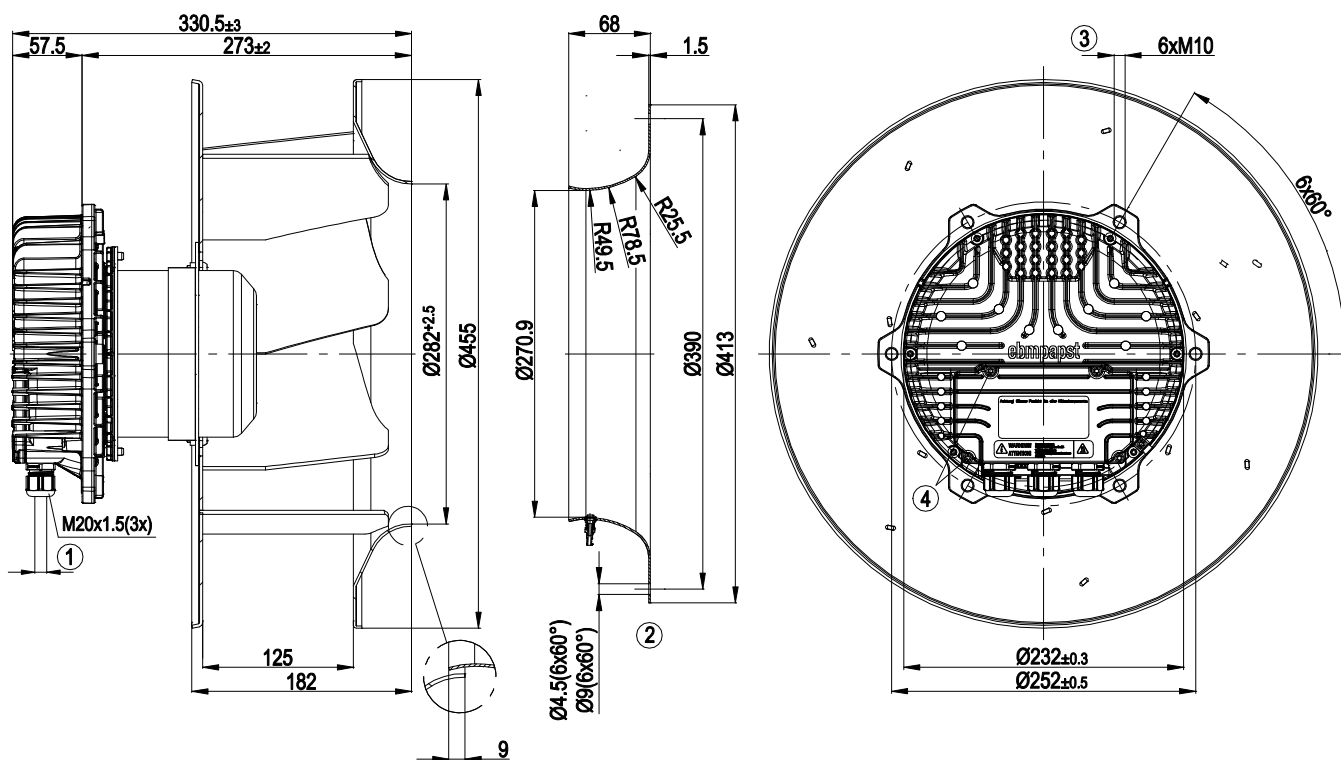


Technical description

Weight	15 kg
Size	400 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2
EMC interference emission	According to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used equipment with a total rated power greater than 1 kW
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE; UKCA
Approval	EAC; UL 1004-7 + 60730-1

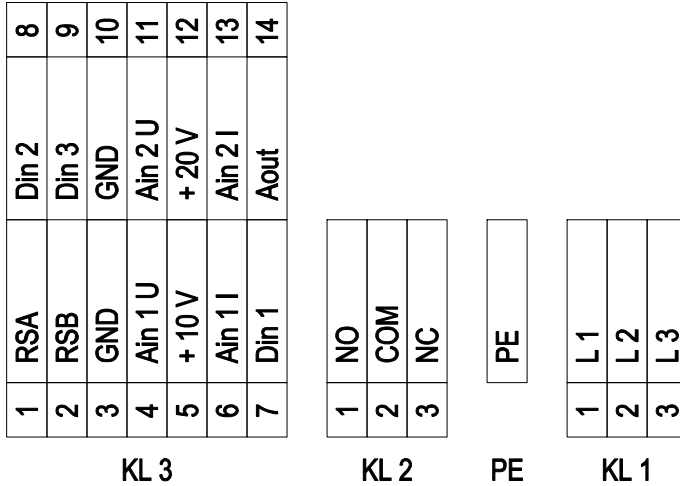


Product drawing



- | | |
|---|---|
| 1 | Cable diameter min. 4 mm, max. 10 mm; tightening torque 4 ± 0.6 Nm |
| 2 | Accessory part: inlet ring 40075-2-4013 with pressure tap not included in scope of delivery, other inlet rings on request |
| 3 | Clearance for screw 12-16 mm |
| 4 | Tightening torque 3.5 ± 0.5 Nm |

Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact; make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV

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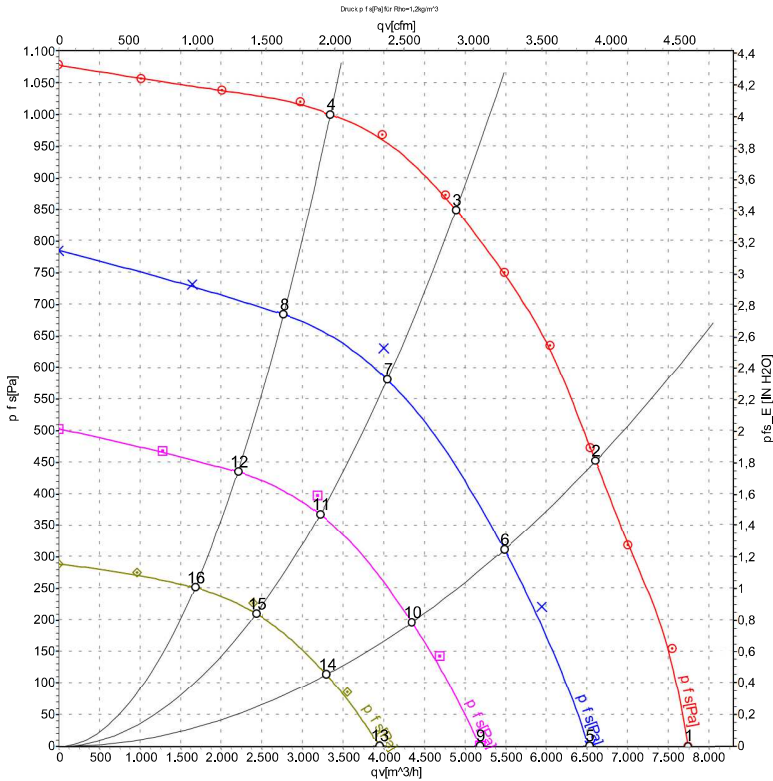
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No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω , adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



Curves: Air performance 50 Hz



Measurement: LU-122009-1
Measurement: LU-122096-1
Measurement: LU-122097-1
Measurement: LU-122098-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{ts}	q _v	P _{ts}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	in. wg
1	400	50	2180	1162	1.76	82	89	95	7745	0	4560	0.00
2	400	50	2180	1562	2.37	76	84	89	6605	450	3890	1.81
3	400	50	2180	1850	2.90	74	81	87	4890	850	2880	3.41
4	400	50	2180	1694	2.56	76	84	90	3345	1000	1970	4.01
5	400	50	1810	672	1.04	77	85	90	6525	0	3840	0.00
6	400	50	1810	877	1.34	72	80	85	5480	318	3225	1.28
7	400	50	1810	1040	1.59	71	78	84	4045	622	2380	2.50
8	400	50	1810	905	1.38	72	79	85	2765	683	1630	2.74
9	400	50	1440	346	0.59	71	79	84	5185	0	3050	0.00
10	400	50	1440	447	0.75	68	74	80	4345	200	2560	0.80
11	400	50	1440	475	0.85	66	73	78	3215	393	1890	1.58
12	400	50	1440	430	0.74	67	74	79	2205	434	1295	1.74
13	400	50	1090	172	0.38	64	73	80	3940	0	2320	0.00
14	400	50	1090	204	0.42	61	69	74	3295	116	1940	0.47
15	400	50	1090	228	0.47	61	67	72	2425	222	1430	0.89
16	400	50	1090	204	0.43	61	67	73	1675	250	985	1.00

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{ts} = Pressure increase

