

R3G500-AG25-01

EC centrifugal fan

backward-curved, single-intake



ebm-papst Mulfingen GmbH & Co. KG

Bachmühle 2 · D-74673 Mulfingen

Phone +49 7938 81-0

Fax +49 7938 81-110

info1@de.ebmpapst.com

www.ebmpapst.com

Limited partnership · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	R3G500-AG25-01	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	1700
Power consumption	W	2500
Current draw	A	3.9
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual		Req. 2015	
01 Overall efficiency η_{es}	%	59.1		55.7	
02 Measurement category		A			
03 Efficiency category		Static			
04 Efficiency grade N		65.4		62	
05 Variable speed drive		Yes			
09 Power consumption P_{ed}	kW			2.52	
09 Air flow q_v	m ³ /h			6960	
09 Pressure increase p_{fs}	Pa			724	
10 Speed (rpm) n	min ⁻¹			1700	
11 Specific ratio*				1.01	

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-116713

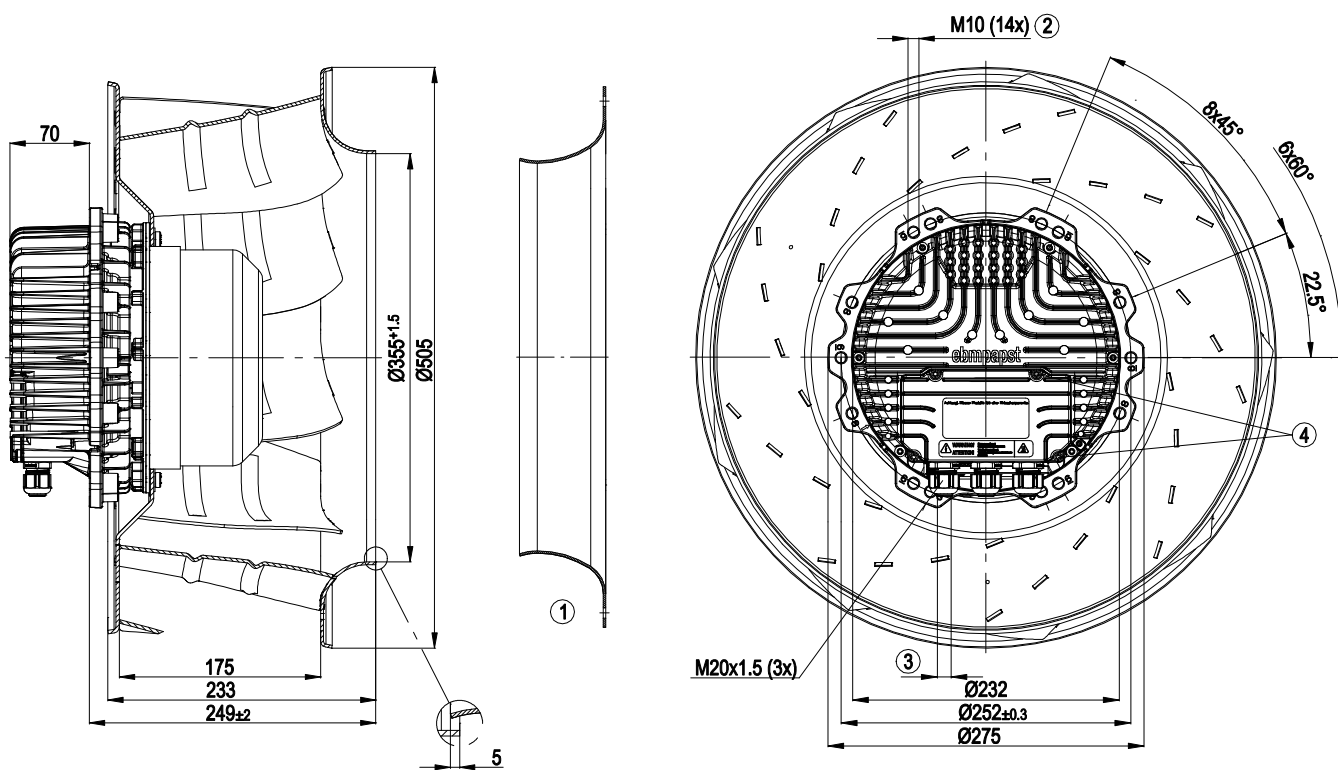


Technical description

Weight	22.7 kg
Size	500 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	9
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used equipment with a total rated power greater than 1 kW
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1



Product drawing



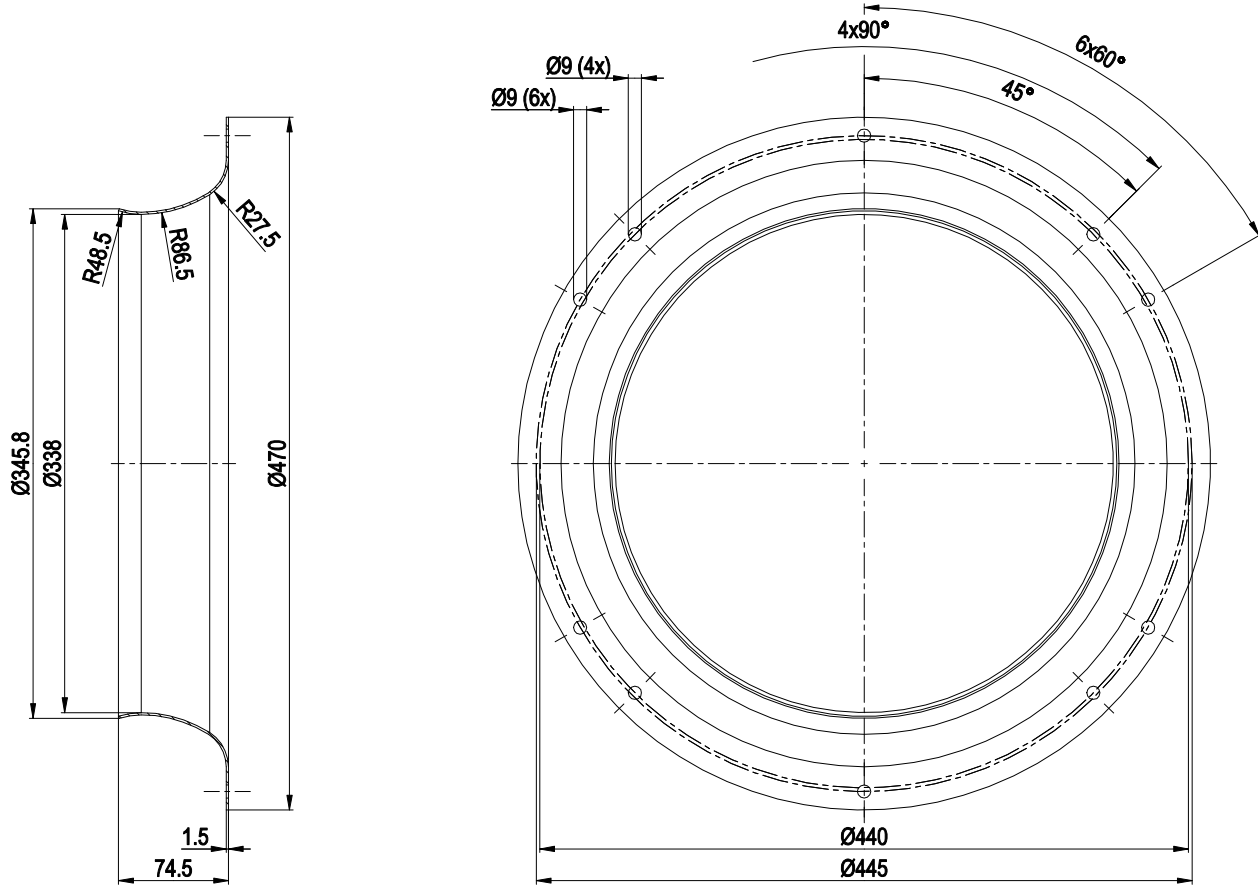
- | | |
|---|--|
| 1 | Accessory part: Inlet ring 63072-2-4013, not included in scope of delivery |
| 2 | Max. clearance for screw 25 mm |
| 3 | Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm |
| 4 | Tightening torque 3.5 ± 0.5 Nm |

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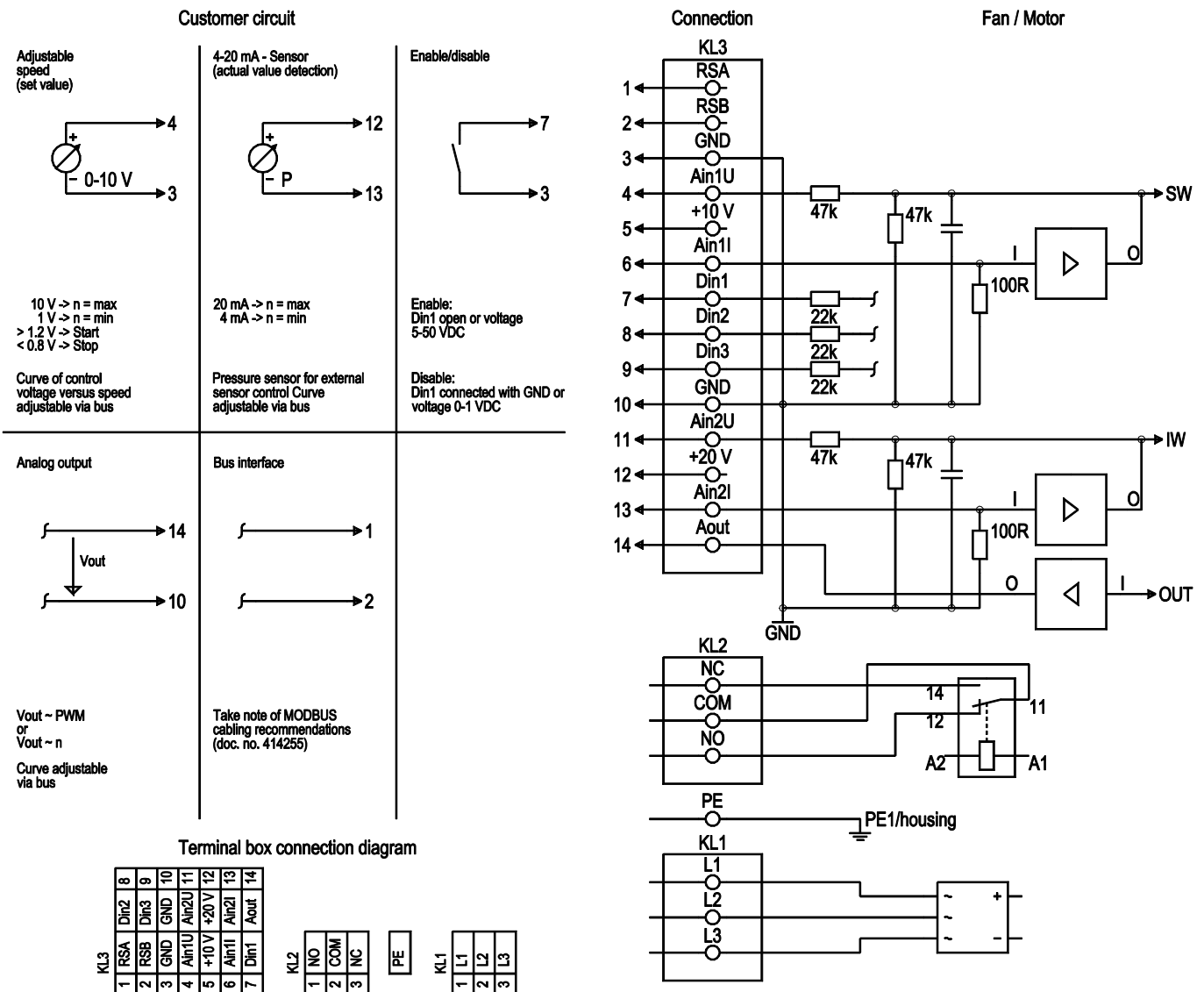
Accessory part



Inlet ring 63072-2-4013



Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply; for nominal voltage range see technical data
KL 1	2	L2	Supply connection, power supply; for nominal voltage range see technical data
KL 1	3	L3	Supply connection, power supply; for nominal voltage range see technical data
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1I; SELV

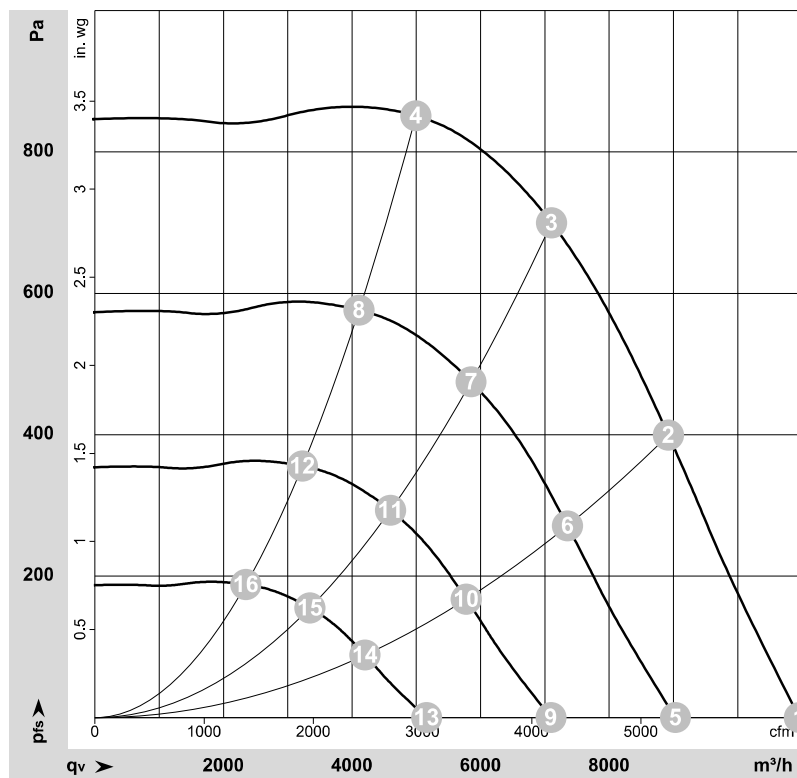
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No.	Conn.	Designation	Function/assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V $\pm 3\%$, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, $R_i = 100 \Omega$, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, $R_i = 100 \text{ k}\Omega$, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V $\pm 25/-10\%$, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV or: +24 VDC input for parameter setting without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, $R_i = 100 \Omega$, adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-116713-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	in. wg
1	3~	400	50	1700	1813	2.78	83	90	95	10960	0	6450	0.00
2	3~	400	50	1700	2291	3.50	78	85	91	8920	400	5250	1.61
3	3~	400	50	1700	2500	3.90	75	82	88	7105	700	4180	2.81
4	3~	400	50	1700	2285	3.47	75	82	89	4995	850	2940	3.41
5	3~	400	50	1400	1014	1.55	79	85	90	9030	0	5315	0.00
6	3~	400	50	1400	1281	1.96	73	80	86	7350	272	4325	1.09
7	3~	400	50	1400	1404	2.14	70	77	83	5855	477	3445	1.91
8	3~	400	50	1400	1272	1.93	70	77	84	4110	577	2420	2.32
9	3~	400	50	1100	492	0.75	73	79	84	7095	0	4175	0.00
10	3~	400	50	1100	621	0.95	67	74	80	5775	168	3400	0.67
11	3~	400	50	1100	681	1.04	64	71	77	4600	294	2705	1.18
12	3~	400	50	1100	617	0.94	64	71	78	3230	356	1900	1.43
13	3~	400	50	800	189	0.29	64	71	76	5160	0	3035	0.00
14	3~	400	50	800	239	0.37	59	66	72	4200	89	2475	0.36
15	3~	400	50	800	262	0.40	56	63	69	3345	156	1970	0.63
16	3~	400	50	800	237	0.36	56	63	70	2350	188	1380	0.75

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

