

backward curved, single inlet

with support structure

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**Nominal data**

Type	K3G800-AQ03-01	
Motor	M3G200-QA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min ⁻¹	960
Power input	W	5800
Current draw	A	9.4
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+40

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		67.7	55.5	59.5
Efficiency grade N		70.2	58	62
Power input P_{ed}	kW	5.8		
Air flow q_v	m ³ /h	21405		
Pressure increase p_{fs}	Pa	636		
Speed n	min ⁻¹	955		

Data established at point of optimum efficiency

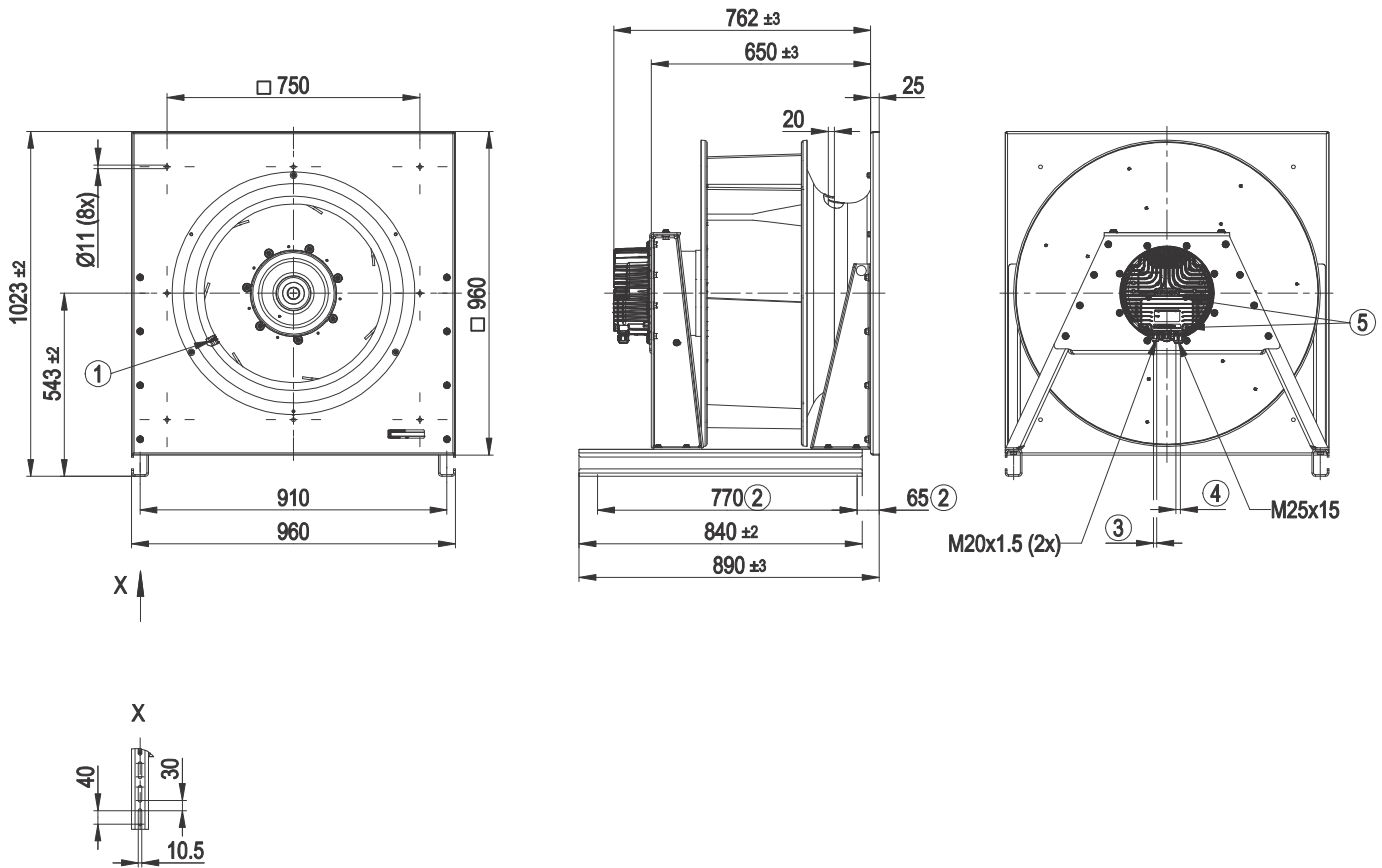


Technical features

Mass	158 kg
Size	800 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of inlet nozzle	Sheet steel, galvanised
Material of support structure	Sheet steel, galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3,5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	GOST; UL 1004-7 + 60730; C22.2 Nr.77 + CAN/CSA-E60730-1

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Product drawing

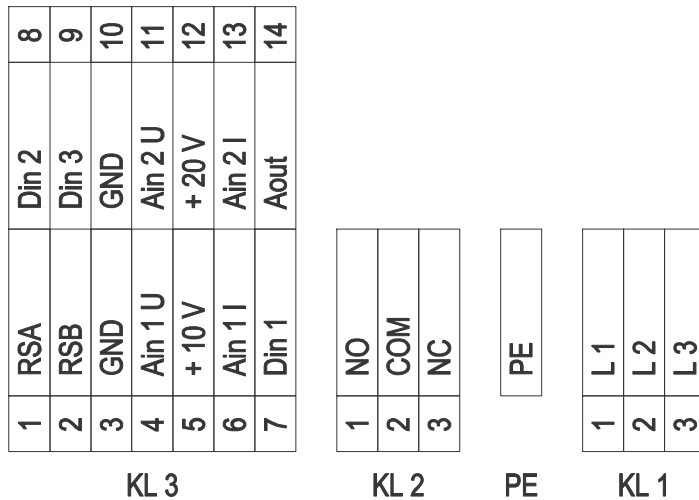


1	Inlet nozzle with bleeder connection for pressure relief (k-factor: 545)
2	Screw-on position for vibration-absorbing elements
3	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4 ± 0.6 Nm
4	Cable diameter: min. 9 mm, max. 16 mm, tightening torque: 6 ± 0.6 Nm
5	Tightening torque 3.5 ± 0.5 Nm

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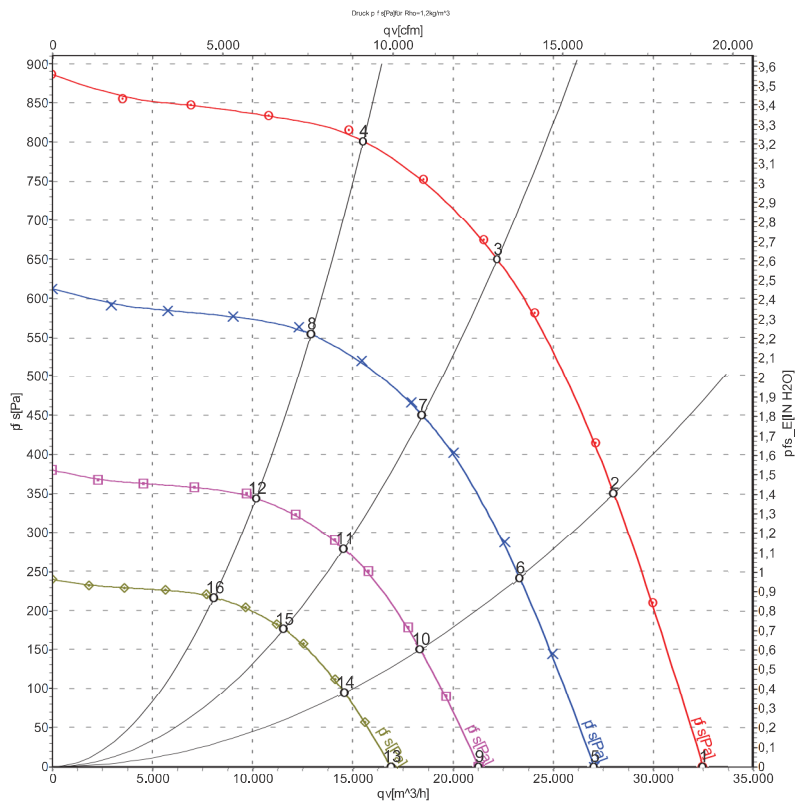
Connection screen



No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Signal ground for control interface KL3
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20 V +/-10 %; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed; function selectable per bus; parametrisable curve.



Charts: Air flow 50 Hz



Measurement: LU-132995

Air performance measured as per ISO 5801
 Installation category A. For detailed
 information on the measuring set-up, please
 contact ebm-papst. Suction-side noise
 levels: L_{wA} measured as per ISO 13347 /
 L_{pA} measured with 1m distance to fan axis.
 The values given are valid under the
 measuring conditions mentioned above and
 may vary according to the actual installation
 situation. With any deviation from the
 standard set-up, the specific values have to
 be checked and reviewed with the unit
 installed.

Measured values

	U	f	n	P _{ed}	I	L _{pA_{in}}	L _{wA_{in}}	L _{wA_{out}}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	400	50	960	3731	6.17	90	97	98	32490	0
2	400	50	960	5130	8.25	82	90	92	28040	350
3	400	50	960	5800	9.40	74	82	86	22210	650
4	400	50	960	5495	8.83	73	81	86	15520	800
5	400	50	800	2151	3.56	86	93	94	27040	0
6	400	50	800	2953	4.75	78	86	88	23320	243
7	400	50	800	3419	5.48	70	78	82	18470	450
8	400	50	800	3161	5.08	69	77	82	12910	556
9	400	50	630	1051	1.74	80	88	89	21300	0
10	400	50	630	1442	2.32	73	81	83	18370	150
11	400	50	630	1670	2.67	65	72	77	14550	279
12	400	50	630	1544	2.48	64	72	77	10170	345
13	400	50	500	525	0.87	75	83	84	16900	0
14	400	50	500	721	1.16	68	76	78	14580	95
15	400	50	500	835	1.34	60	67	72	11550	176
16	400	50	500	772	1.24	59	67	72	8070	217

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · L_{pA_{in}} = Sound pressure level inlet side · L_{wA_{in}} = Sound power level inlet side · L_{wA_{out}} = Sound power level outlet side

qv = Air flow · p_{fs} = Pressure increase

