

KARTA KATALOGOWA

R3G400-AQ23-01

Wentylator promieniowy EC Plug fan, łopatki zakrzywione do tyłu, jednostronnie ssący

Producent: ebm-papst

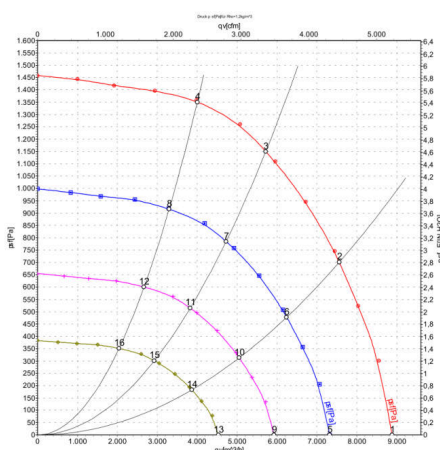


Dane znamionowe		Budowa	
Napięcie znamionowe	3~ 400 V (380...480 V)	Wielkość	400 mm
Częstotliwość	50/60 Hz	Silnik	M3G150-FF
Prędkość obrotowa	2550 obr/min	Materiał wirnika	blacha aluminiowa
Pobór mocy	3000 W	Obudowa elektroniki	odlew aluminiowy
Pobór prądu	4,6 A	Liczba łopatek	7
Maks. wydajność	8850 m³/h	Kierunek obrotów	w prawo, patrząc na wirnik
Maks. ciśnienie statyczne	1450 Pa	Stopień ochrony	IP54
Temperatura otoczenia	-25...+60 °C	Klasa izolacji	F
Regulacja obrotów	0-10 V / PWM, MODBUS RTU	Zabezpieczenie silnika	ochrona przed odwrotną polaryzacją i zablokowaniem wirnika
		Łożyskowanie	kulkowe
		Podłączenie	skrzynka zaciskowa
		Masa	21 kg

Dane ErP (UE 327/2011)	
Sprawność całkowita	62,8 %
Przepływ w pkt. optymalnym	5960 m³/h
Przyrost ciśnienia	1064 Pa

Charakterystyka przepływowa (50 Hz)

Charts: Air flow 50 Hz



Measurement: LU-121571

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Dane na okładce wg karty katalogowej producenta ebm-papst (oryginał na kolejnych stronach).
Wartości przy maksymalnym obciążeniu; producent zastrzega możliwość zmian.

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EC centrifugal fan - Plug fan

backward curved, single inlet


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Nominal data

Type	R3G400-AQ23-01	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	2550
Power input	W	3000
Current draw	A	4.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+60

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Closed-loop speed control	Integrated
Specific ratio*	1,01

* Specific ratio = $1 + p_{sf} / 100\,000$

		Actual	Request 2013	Request 2015
Overall efficiency η_e		62,8	52,4	56,4
Efficiency grade N		68,4	58	62
Power input P_e	kW	2,95		
Air flow q_v	m ³ /h	5960		
Pressure increase Total p_{sf}	Pa	1064		
Speed n	min ⁻¹	2540		

Data established at point of optimum efficiency


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Technical features

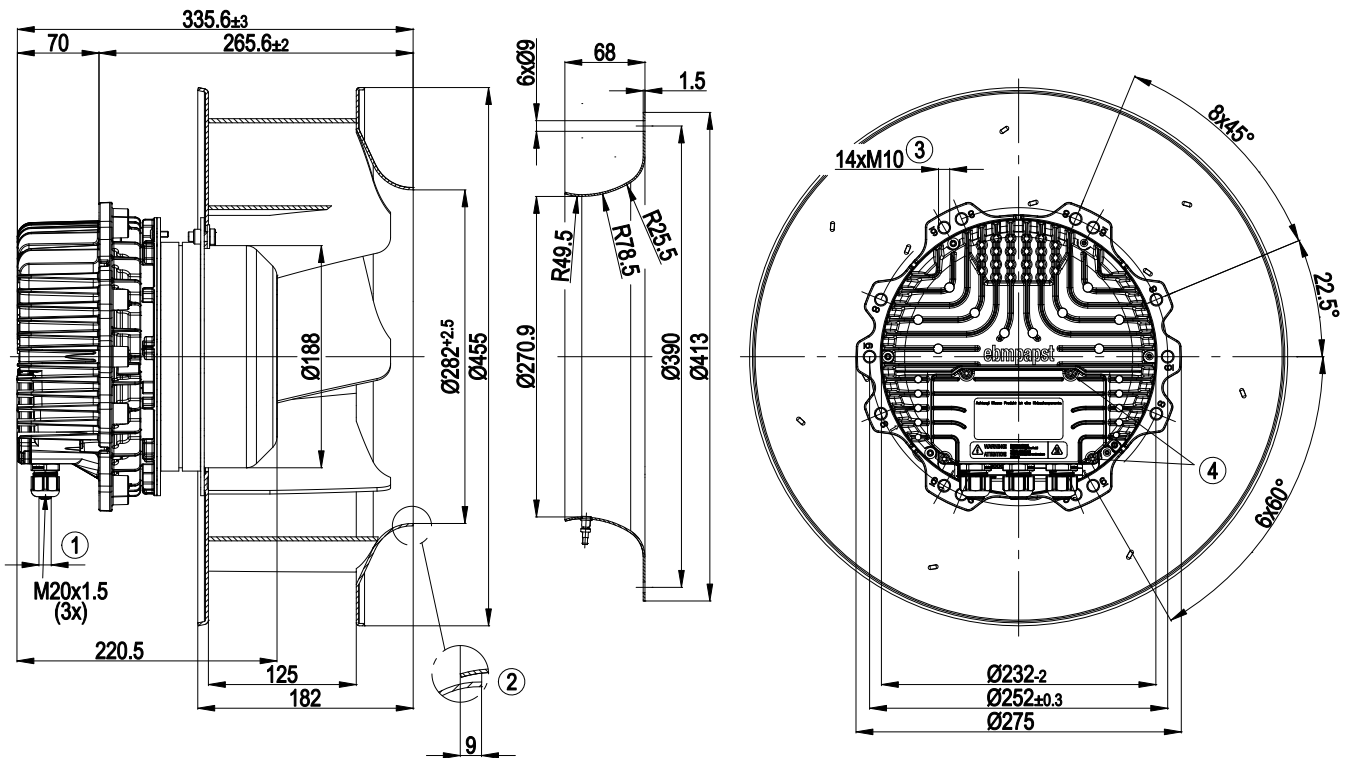
Mass	21 kg
Size	400 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- RS485 MODBUS RTU - PFC, passive - Control input 0-10 VDC / PWM - Overtemperature-protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - External 24 V input (setting parameters)
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Leakage current	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; UL 1004-7 + 60730

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Product drawing



1	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm
2	Accessory part: inlet nozzle 40075-2-4013 with a pressure tap not included in the standard scope of delivery; other inlet nozzles on request
3	Depth of screw max. 25 mm
4	Tightening torque 3.5±0.5 Nm

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Connection screen

8	9	10	11	12	13	14
Din 2	Din 3	GND	Ain 2 U	+ 20 V	Ain 2 I	Aout
RSA	RSB	GND	Ain 1 U	+ 10 V	Ain 1 I	Din 1
1	2	3	4	5	6	7

KL 3

NO	COM	NC
1	2	3

KL 2

PE

PE

L1	L2	L3
1	2	3

KL 1

No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL 2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL 2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Signal ground for control interface KL3
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20 V +25/-10 %; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed; function selectable per bus; parametrisable curve.

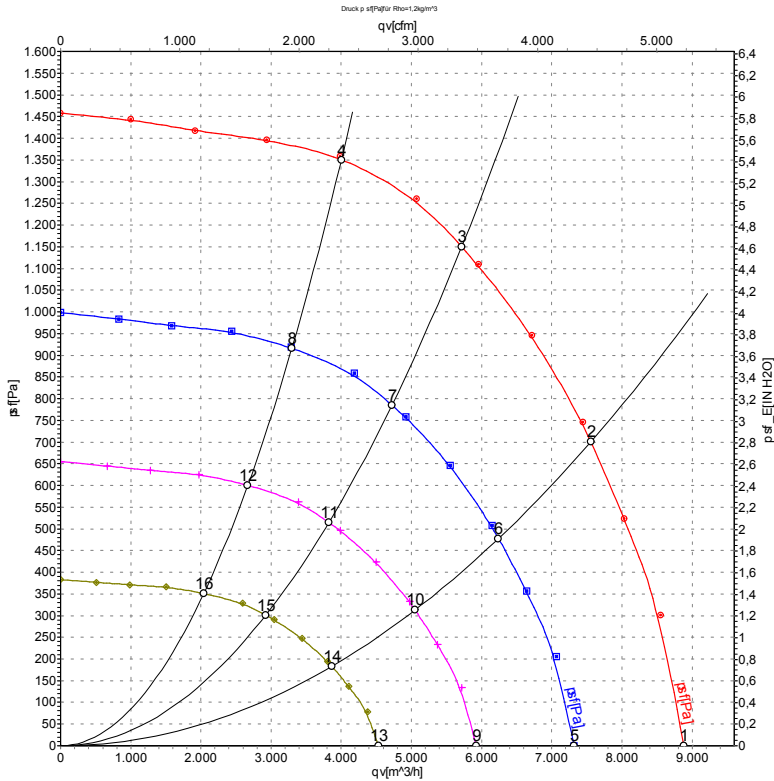


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Measurement: LU-121371

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Measured values

	U	f	n	Pe	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	Pst
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	400	50	2550	1972	3.02	86	93	99	8880	0
2	400	50	2550	2697	4.13	80	87	94	7555	700
3	400	50	2550	3000	4.60	78	85	92	5715	1150
4	400	50	2550	2792	4.27	80	88	94	4000	1350
5	400	50	2100	1103	1.69	82	89	95	7315	0
6	400	50	2100	1517	2.33	76	83	90	6240	479
7	400	50	2100	1668	2.56	74	81	88	4725	786
8	400	50	2100	1555	2.38	75	84	89	3295	918
9	400	50	1700	585	0.90	77	84	90	5920	0
10	400	50	1700	805	1.23	71	78	85	5050	314
11	400	50	1700	885	1.36	69	76	83	3825	515
12	400	50	1700	825	1.26	71	79	85	2665	602
13	400	50	1300	262	0.40	71	78	84	4530	0
14	400	50	1300	360	0.55	65	72	79	3865	184
15	400	50	1300	396	0.61	64	71	78	2925	301
16	400	50	1300	369	0.56	65	73	79	2040	352