

KARTA KATALOGOWA

R3G400-PI92-01

Wentylator promieniowy EC RadiPac, łopatki zakrzywione do tyłu, jednostronnie ssący

Producent: ebm-papst



Zdjęcie poglądowe

Dane znamionowe

Napięcie znamionowe	3~ 400 V (380...480 V)
Częstotliwość	50/60 Hz
Prędkość obrotowa	2450 obr/min
Pobór mocy	2500 W
Pobór prądu	3,8 A
Maks. wydajność	10020 m³/h
Maks. ciśnienie statyczne	1250 Pa
Temperatura otoczenia	-25...+40 °C

Budowa

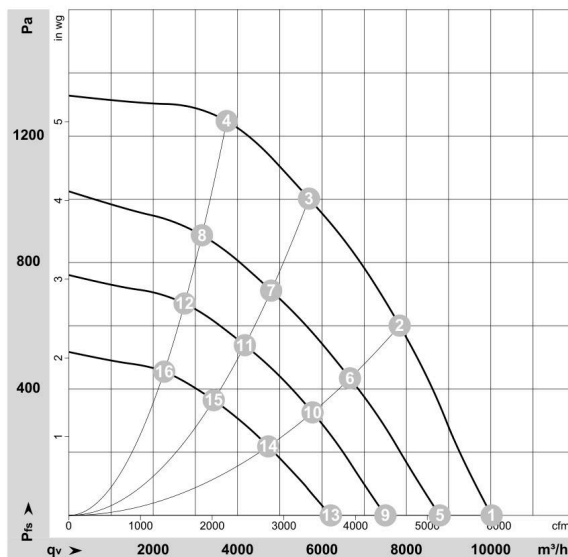
Średnica wirnika	400 mm
Materiał wirnika	blacha aluminiowa
Liczba łopatek	5
Stopień ochrony	IP54
Klasa izolacji	B
Zabezpieczenie silnika	termik (TOP)
Masa	14,6 kg

Dane ErP (UE 327/2011)

Sprawność całkowita	70 %
Przepływ w pkt. optymalnym	6600 m³/h
Przyrost ciśnienia	865 Pa
Regulacja obrotów	tak (0-10 V / PWM / MODBUS)

Charakterystyka przepływowa

Charts: Air flow 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-176408-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Dane na podstawie karty producenta ebm-papst (oryginał na kolejnych stronach).

Wartości znamionowe dla punktu maksymalnego obciążenia; producent zastrzega możliwość zmian.

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R3G400-PI92-01

EC centrifugal fan - RadiPac

backward curved, single inlet

Nominal data

Type	R3G400-PI92-01	
Motor	M3G112-IA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	2450
Power input	W	2500
Current draw	A	3.8
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data in accordance with ecodesign regulation EU 327/2011 (EN 17166)

		Actual	Request 2015			
01 Overall efficiency η_{es}	%	70	55.5	09 Power input P_{ed}	kW	2.39
02 Measurement category		A		09 Air flow q_v	m³/h	6600
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	865
04 Efficiency grade N		76.5	62	10 Speed (rpm) n	min ⁻¹	2480
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$ LU-176408



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Technical features

Mass	14.6 kg
Size	400 mm
Motor size	112
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	5
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP54
Insulation class	"B"
Humidity (F) / environmental protection class (H)	H1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical connection	Terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	CSA C22.2 no. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

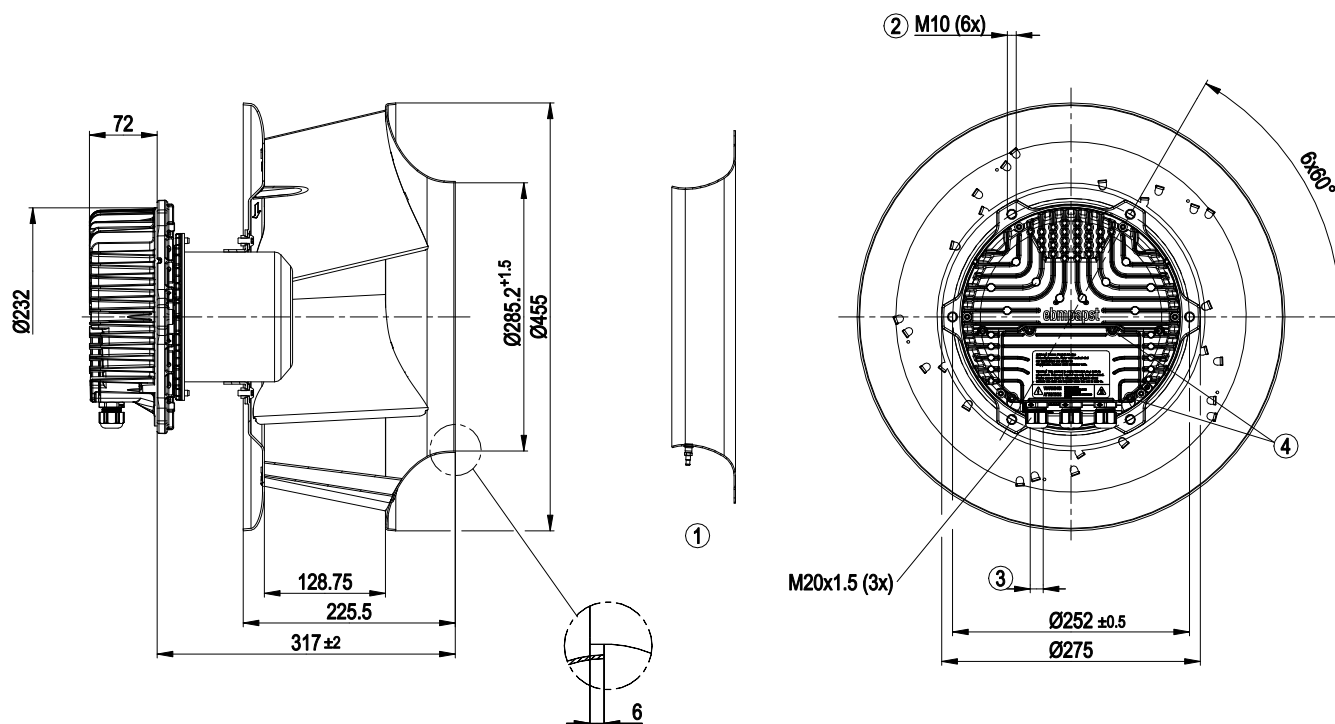


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Product drawing



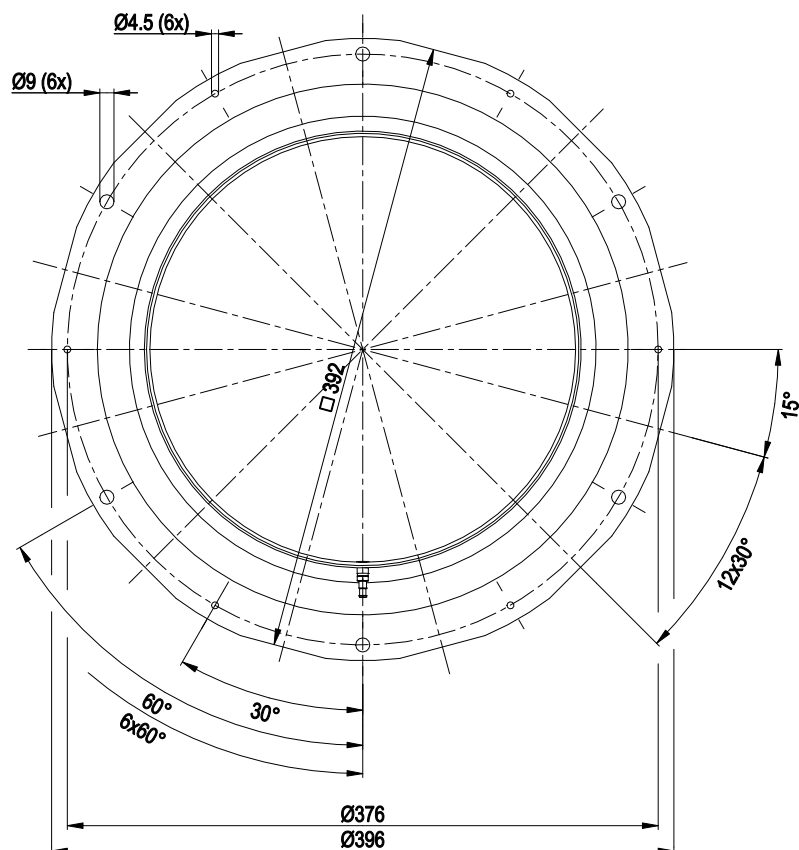
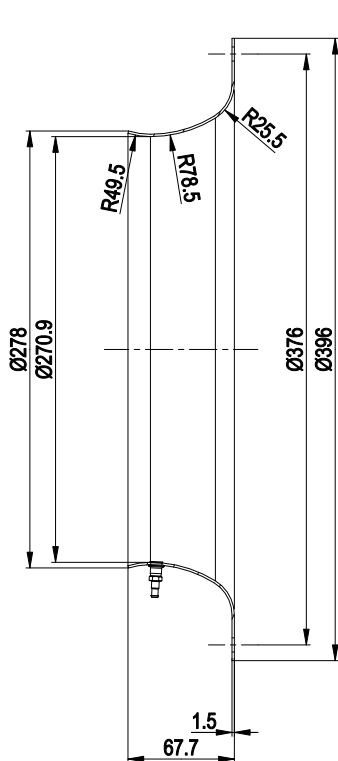
1	Accessory part: Inlet nozzle 40078-2-4013 with pressure tap (k-factor: 188) not included in scope of delivery
2	Thread reach max. 20 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
4	Tightening torque 3.5±0.5 Nm

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Accessory part



Inlet nozzle 40078-2-4013 with pressure tap not included in scope of delivery

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Connection screen

8	9	10	11	12	13	14
Din 2	Din 3	GND	Ain 2 U	+ 20 V	Ain 2 I	Aout
RSA	RSB	GND	Ain 1 U	+ 10 V	Ain 1 I	Din 1
1	2	3	4	5	6	7

KL 3

NO	COM	NC
1	2	3

KL 2

PE

PE

L1	L2	L3
1	2	3

KL 1

No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV



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No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

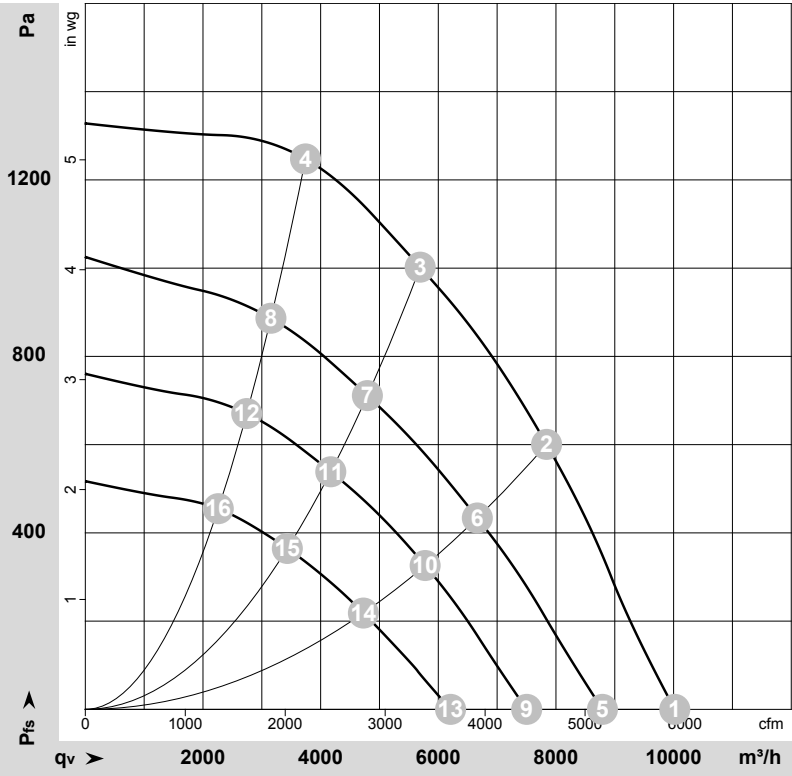


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Measured values

	Conn.	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	in. wg
1	Y	400	50	2450	1323	2.07	89	96	96	10020	0	5900	0.00
2	Y	400	50	2450	2210	3.38	77	85	88	7840	600	4615	2.41
3	Y	400	50	2450	2500	3.80	74	82	86	5690	1000	3350	4.01
4	Y	400	50	2450	2336	3.57	78	86	90	3745	1250	2205	5.02
5	Y	400	50	2180	921	1.50	84	91	92	8790	0	5175	0.00
6	Y	400	50	2100	1376	2.15	72	80	84	6665	434	3920	1.74
7	Y	400	50	2080	1479	2.30	70	77	83	4795	712	2820	2.86
8	Y	400	50	2090	1420	2.22	74	81	85	3155	887	1855	3.56
9	Y	400	50	1875	626	1.10	80	87	88	7505	0	4415	0.00
10	Y	400	50	1825	923	1.50	69	77	81	5775	326	3400	1.31
11	Y	400	50	1810	994	1.60	66	74	80	4175	539	2455	2.16
12	Y	400	50	1815	955	1.55	69	77	82	2745	671	1615	2.69
13	Y	400	50	1545	377	0.73	74	83	85	6210	0	3655	0.00
14	Y	400	50	1500	545	1.00	64	72	77	4725	220	2780	0.88
15	Y	400	50	1490	585	1.05	62	69	76	3435	365	2020	1.47
16	Y	400	50	1495	566	1.03	64	72	78	2260	455	1330	1.83

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side
LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

