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Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	R3G450-PB24-01	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	2600
Power consumption	W	5250
Current draw	A	8
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment

Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	69.2	59	09 Power consumption P_{ed}	kW	5.22
02 Measurement category		A		09 Air flow q_v	m ³ /h	7865
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	1606
04 Efficiency grade N		72.2	62	10 Speed (rpm) n	min ⁻¹	2620
05 Variable speed drive		Yes		11 Specific ratio*		1.02

Data obtained at optimum efficiency level.

* Specific ratio = $1 + p_b / 100\,000\text{ Pa}$

LU-176459

The efficiency values displayed for achieving conformity with the Ecodesign Regulation EU 327/2011 has been reached with defined air duct components (e.g. inlet rings). The dimensions must be requested from ebm-papst. If other air conduction geometries are used on the installation side, the ebm-papst evaluation loses its validity/the conformity must be confirmed again. The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2 (2a) (motors completely integrated into a product).

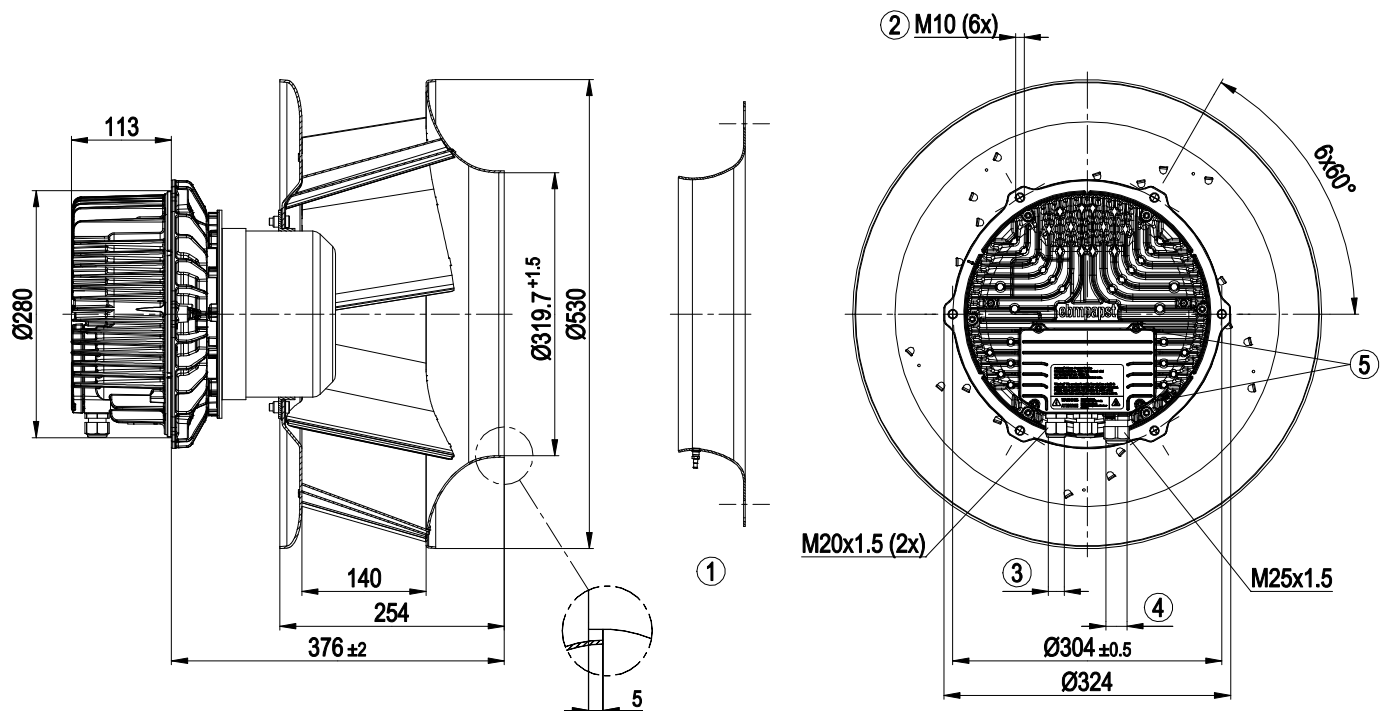


Technical description

Weight	31 kg
Size	450 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used equipment with a total rated power greater than 1 kW
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; UKCA; CE
Approval	UL 1004-7 + 60730-1; CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC

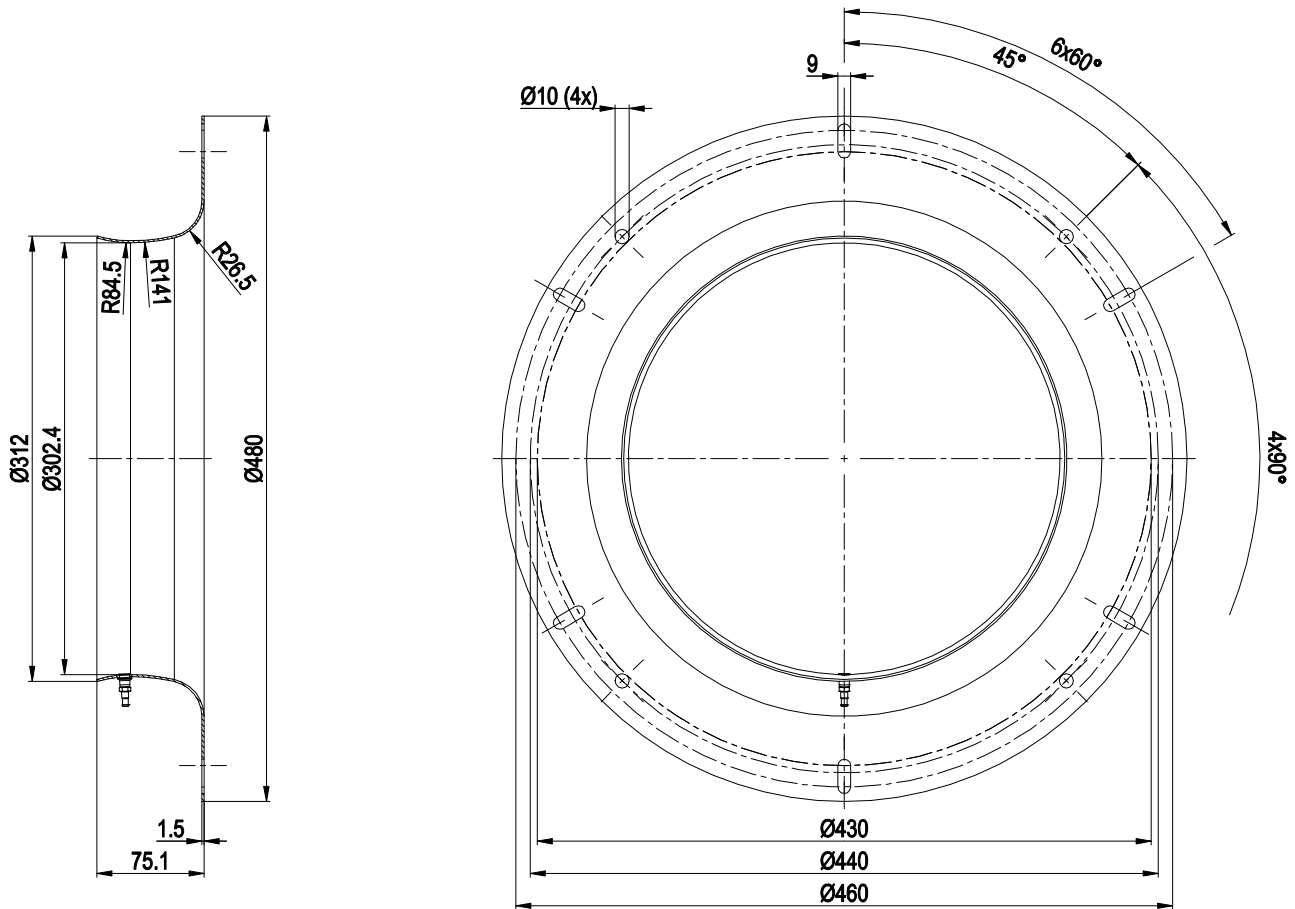


Product drawing



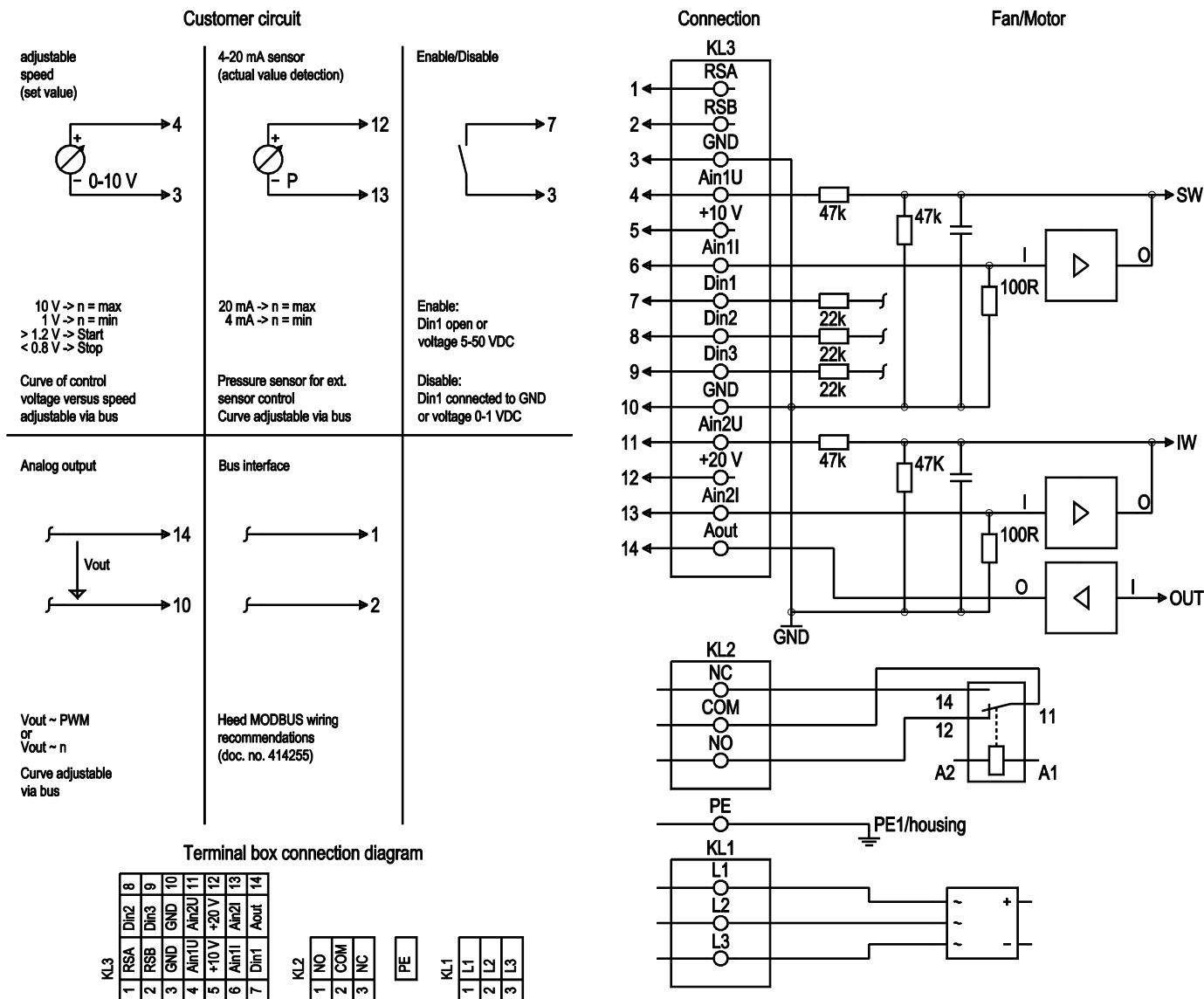
1	Accessory part: Inlet ring 45075-2-4013 with pressure tap (k-factor: 240) not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Cable diameter min. 9 mm, max. 16 mm, tightening torque 6 ± 0.9 Nm
5	Tightening torque 3.5 ± 0.5 Nm

Accessory part



Inlet ring 45075-2-4013 with pressure tap (k-factor: 240)

Connection diagram

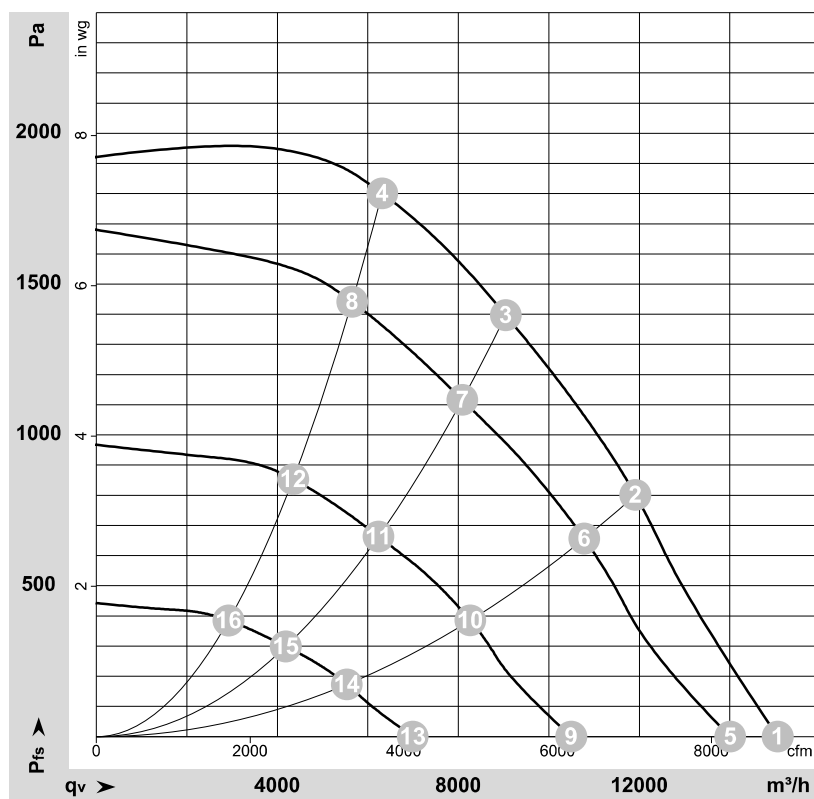


No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply, phase, see nameplate for voltage range
KL 1	2	L2	Supply connection, power supply, phase, see nameplate for voltage range
KL 1	3	L3	Supply connection, power supply, phase, see nameplate for voltage range
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL 2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL 2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface, SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV

No.	Conn.	Designation	Function/assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V $\pm$ 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω , adjustable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: Direction of action of integrated controller, according to EEPROM setting, the direction of action of the integrated controller can be selected as normal/inverse via bus or digital input Normal: Pin open or applied voltage 5-50 VDC Inverse: Bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 k Ω , adjustable curve, only usable as alternative to input Ain2 I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V $\pm$ 25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω , adjustable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analog output 0-10 V, max. 5 mA, output of current motor modulation level; adjustable curve; SELV



Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-176459-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	2600	3067	4.78	95	102	102	15055	0	8860	0.00
2	400	50	2600	4640	7.13	85	92	97	11910	800	7010	3.21
3	400	50	2600	5250	8.00	80	87	96	9045	1400	5325	5.62
4	400	50	2600	5141	7.89	84	91	97	6320	1800	3720	7.23
5	400	50	2430	2502	3.95	92	99	100	14010	0	8245	0.00
6	400	50	2360	3460	5.36	82	89	96	10780	660	6345	2.65
7	400	50	2335	3767	5.81	77	84	95	8090	1117	4760	4.48
8	400	50	2345	3677	5.68	80	87	95	5655	1445	3325	5.80
9	400	50	1840	1122	2.04	84	92	94	10495	0	6175	0.00
10	400	50	1815	1598	2.67	75	82	90	8260	388	4865	1.56
11	400	50	1800	1761	2.89	71	78	89	6235	663	3670	2.66
12	400	50	1805	1708	2.82	74	81	89	4350	855	2560	3.43
13	400	50	1235	402	0.84	74	81	85	6990	0	4115	0.00
14	400	50	1215	543	1.08	64	71	77	5535	176	3260	0.71
15	400	50	1210	594	1.17	62	69	76	4185	299	2465	1.20
16	400	50	1210	574	1.14	64	71	77	2920	386	1720	1.55

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase

