

KARTA KATALOGOWA

R3G500-AP25-01

Wentylator promieniowy EC, łopatki zakrzywione do tyłu, jednostronnie ssący

Producent: ebm-papst



Dane znamionowe

Napięcie znamionowe	3~ 400 V (380...480 V)
Częstotliwość	50/60 Hz
Prędkość obrotowa	1780 obr/min
Pobór mocy	2825 W
Pobór prądu	4,3 A
Maks. wydajność	12610 m³/h
Maks. ciśnienie statyczne	1075 Pa
Temperatura otoczenia	-25...+60 °C

Budowa

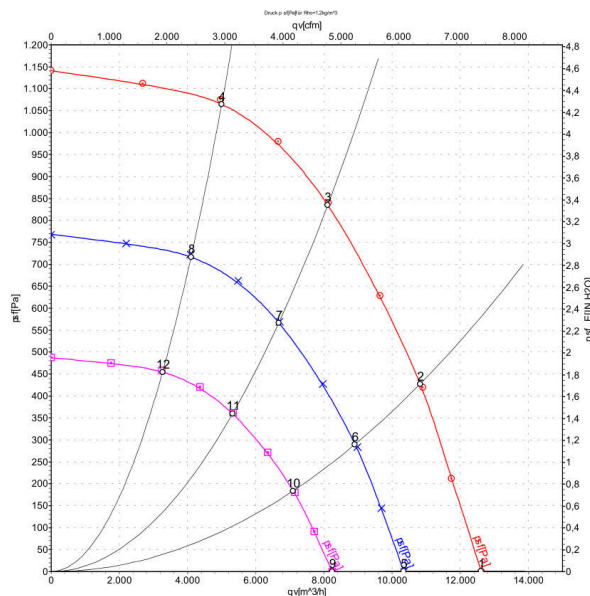
Średnica wirnika	500 mm
Materiał wirnika	blacha aluminiowa
Liczba łopatek	7
Stopień ochrony	IP54
Klasa izolacji	F
Zabezpieczenie silnika	ochrona przed zablokowaniem wirnika
Masa	25 kg

Dane ErP (UE 327/2011)

Sprawność całkowita	66,5 %
Przepływ w pkt. optymalnym	8140 m³/h
Regulacja obrotów	tak (0-10 V / PWM / MODBUS)

Charakterystyka przepływowa

Charts: Air flow 50 Hz



Measurement: LU-128476

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Dane na podstawie karty producenta ebm-papst (oryginał na kolejnych stronach).

Wartości znamionowe dla punktu maksymalnego obciążenia; producent zastrzega możliwość zmian.

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R3G500-AP25-01

EC centrifugal fan - Plug fan

backward curved, single inlet



Nominal data

Type	R3G500-AP25-01	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		me
State		prelim.
Speed	min ⁻¹	1780
Power input	W	2825
Current draw	A	4.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+60

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Closed-loop speed control	Integrated
Specific ratio*	1,01

* Specific ratio = 1 + p_{sf} / 100 000

		Actual	Request 2013	Request 2015
Overall efficiency η_e		66,5	52,3	56,3
Efficiency grade N		72,2	58	62
Power input P _e	kW	2,86		
Air flow q _v	m³/h	8140		
Pressure increase Total p _{sf}	Pa	799		
Speed n	min ⁻¹	1790		

Data established at point of optimum efficiency



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Technical features

Mass	25 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- RS485 MODBUS RTU - PFC, passive - Control input 0-10 VDC / PWM - Overtemperature-protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - External 24 V input (setting parameters)
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Leakage current	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; UL 1004-7 + 60730

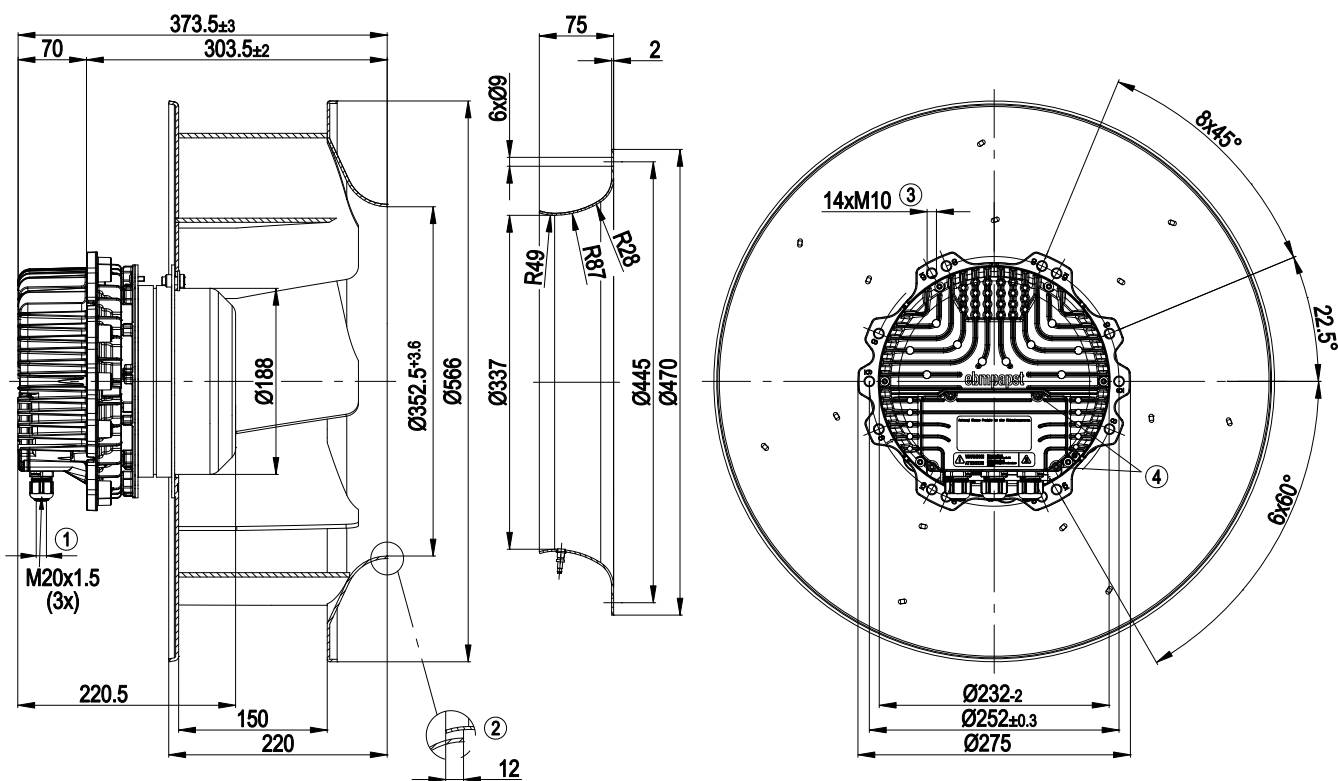


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Product drawing



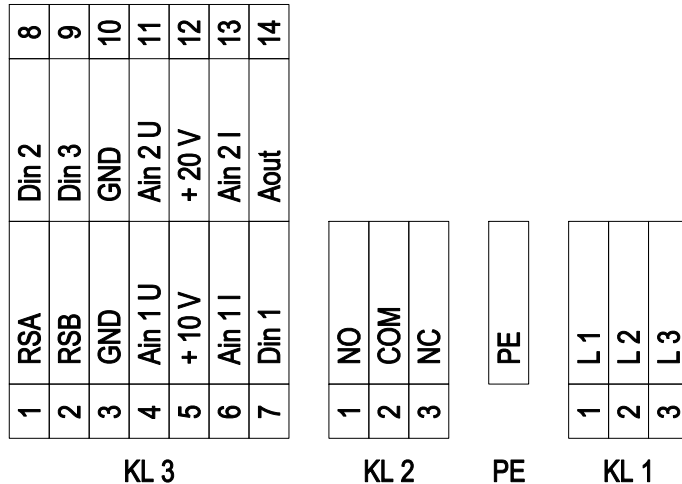
1	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm
2	Accessory part: inlet nozzle 64025-2-4013 with a pressure tap not included in the standard scope of delivery; other inlet nozzles on request
3	Depth of screw max. 25 mm
4	Tightening torque 3.5±0.5 Nm

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Connection screen



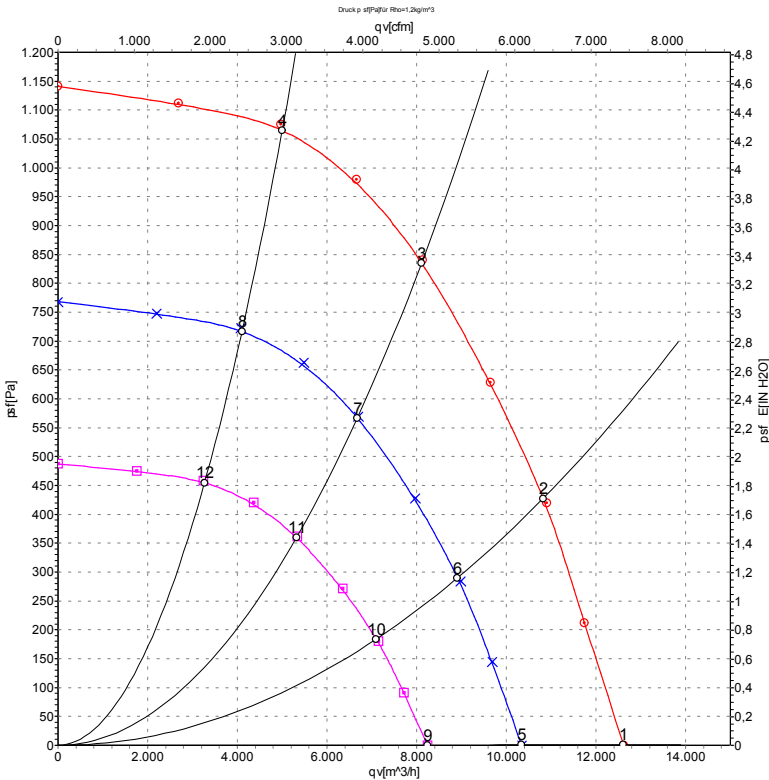
No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Signal ground for control interface KL3
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20 V +/-25/-10 %; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed; function selectable per bus; parametrisable curve.

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installed.

Measured values

	U	f	n	P _e	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	P _{sf}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	1780	1985	3.09	87	94	99	12610	0
2	400	50	1780	2530	3.90	81	89	93	10820	435
3	400	50	1780	2825	4.30	76	83	88	8110	840
4	400	50	1780	2692	4.14	78	85	90	5000	1075
5	400	50	1475	1094	1.70	83	90	95	10340	0
6	400	50	1475	1411	2.18	77	84	89	8910	294
7	400	50	1475	1602	2.47	72	79	84	6680	572
8	400	50	1475	1484	2.28	74	80	86	4100	722
9	400	50	1175	553	0.86	78	85	90	8240	0
10	400	50	1175	714	1.10	72	80	84	7100	187
11	400	50	1175	810	1.25	67	74	79	5320	363
12	400	50	1175	750	1.15	69	75	81	3265	458

